Submit original with signatures + 1 copy + electronic copy to UAF Governance.

See http://www.uaf.edu/uafgov/faculty/cd for a complete description of the rules governing curriculum & course changes.

		TRIAL COURS	E OR NE	w co	URSE PRO	POSAL			
JBMITTED BY:	at sold all sold		3532			R. Frank			
Department	Electrical &Computer Engineering			College/School		CEN			
Prepared by	Seta BOGOSYAN			Phone		474-275			
Email Contact	sbogosyan@alaska.edu			Faculty Contact		Seta Bogosya			
1. ACTION DE	SIRED (CHECK ON	E):	l Course			New	Course	X	
2. COURSE ID	ENTIFICATION:	Dept	EE		Course #	EE 675	No. of	Credits	3
	/lower division ober of credits:	This is a gra mechanics a undergradua also take the dynamics, an credits.	nd auton ates with course.	natic co the pro The co	ontrol . Ho erequisites urse requi	wever, upposed of physics res covera	per divisi s, math, a ge of kine	ion nd contr matics,	ol could
. PROPOSED	COURSE TITLE:		ROBOT MODELING AND CONTROL						
4. To be CROSS LISTED?		No		Dept:			rse #		
	roval of both departi		and the same		at end of fo	Transcript execution of			
5. To be STACKED?		No	No If yes, Dept. Course #				eg top (a section)		
. SEMESTER &	YEAR OF FIRST C			Fi	Demand rst offered urse.	Warrants			COMMUNICATION
must be approved	ours may not be com I by the college or si I by the core review MAT: apply) MAT (specify) ery (specify	chool's curriculun	2 2	Furtherm 3	er credit. And core, any cor	e course con	npressed interpressed to	less than s	six weeks
9. CONTACT H Note: # of credi 1600 minutes in	ts are based on cont n non-science lab=1 n with the syllabus. S	act hours. 800 m credit. 2400-480	hours/ inutes of le 0 minutes	weeks cture=1 of praction	credit. 2400 cum=1 credi	t. 2400-800	lab in a scio	hours ence cours of internshi	ip=1 credi
COMPLETE CA	ATALOG DESCRIP	TION including	dept., nu	ımber, t	title and cro	edits (50 we	ords or les	s, if poss	ible):
homogened kinematics	Robot Modeli ous transform ; velocity kind nt joint contro	ations; Dena ematics, Jaco	vit-Ha biens;	rtenbe dynar	erg para	meters, f modelin	orward g; robot	and in	verse ol:

torque, inverse dynamics control with the use of Matlab/Simulink, kinematics and control related demonstrations on the PUMA 560 manipulator (3+0).

manual. If ju	SSIFICATIONS: (ustification is need			e approved crite S = Social Scien	A CONTRACTOR	Page 10 & 17 of the
	ourse be used to f ccalaureate core?	ulfill a requirem	ent		YES	NO NO
	ck which core required the second core in the secon		ld be used to fu = Writing Intensiv		Natura	Science, Format 8
12. COURSE REPE	ATABILITY: repeatable for cre	dit?	YES	N	IO X	
	Indicate why the the the course follow					
How many	times may the cou	rse be repeated	for credit?			TIMES
	e can be repeated nay be earned for		edit, what is the	maximum nun	nber of credit	CREDITS
13. GRADING SYST		ly one. ASS/FAIL:				
RESTRICTIONS ON	NENROLLMENT (if any)		SET BETTER		
14. PREREQUISITE						tems, and mechanics.
		required before				
RECOMMEND						ience with MATLAB
	Classes, etc. tha			to complete pr	rior to this cou	irse.
15. SPECIAL REST	RICTIONS, CON	DITIONS	none	SARRENCE VICTOR		
16. PROPOSED C Has a memo been Yes/No		none h your dean to t	the Provost & V	CAS for fee app	roval?	
17. PREVIOUS HIS Has the cours	TORY se been offered as	special topics o	r trial course pre	eviously?		yes
If yes, give semester, year, course #, etc.: Fall 2004, Fall 2006, Fall 2009.						
18. ESTIMATED IM WHAT IMPA	IPACT CT, IF ANY, WILL	THIS HAVE ON	I BUDGET, FAC	ILITIES/SPACE,	FACULTY, ET	C.
None, will be	e offered in place	e of another gr	aduate class.			
adequacy of lib	acted the library c	tions, equipmen	pment officer (I nt, and services o	ljensen@alaska available for the	n.edu, 474-669 e proposed cou	95) with regard to the urse? If so, give date of
No X	Yes	From previous for the cours		there is adequ	ate material a	vailable at the library
	PROGRAMS/DEPT ns/departments ion on the Programs	vill be affected				
Students from course. ECE taking it.	ı all graduate pr ıas already offer	ograms, or unced	dergraduate o for 3 times, wi	ptions in ECE th a good num	and ME cou	ald benefit from this disciplinary students

21. POSITIVE AND NEGATIVE IMPACTS

Please specify **positive and negative** impacts on other courses, programs and departments resulting from the proposed action.

No negative impacts expected on any course or program, but certainly some positive impact due to the application oriented content of this course, demonstrating the students where to use their acquired knowledge in mechanics and math, as well as providing them a good opportunity to see semi-sophisticated applications of control theory (which they do not see in any other course).

JUSTIFICATION FOR ACTION REQUESTED

The purpose of the department and campus-wide curriculum committees is to scrutinize course change and new course applications to make sure that the quality of UAF education is not lowered as a result of the proposed change. Please address this in your response. This section needs to be self-explanatory. Use as much space as needed to fully justify the proposed course.

This course has always attracted a good number of graduate students in the past (on average about 6-8) as it provides a good opportunity for students to use their knowledge on motors, mechanical systems, control and programming in various motion control systems. As also mentioned above, this course is the only place the students will see the practical benefits of "control", which is not too transparent to most, taking EE 471. The provided information is not limited to robots, but to all systems that are required to move for a certain application. The potential and importance of the content in a variety of engineering domains make this course very worthwhile for electrical and computer engineering students as well as those of ME department. Another important aspect of the course is that this course also offers the only available material in our curriculum on modeling and control of servo motors and drives, which are ubiquitously used in industry, and certainly not covered in our electrical machinery course (EE 303).

Date 9/29/16
Date 10/15/10
Date 10/15/10
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Date
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O THE GOVERNANCE OFFICE
Date
e

	Date
Signature, Chair, Program/Department of:	Date
	Date
Signature, Chair, College/School Curriculum Council for:	Duc
	Date

ATTACH COMPLETE SYLLABUS (as part of this application).

Note: The guidelines are online: http://www.uaf.edu/uafgov/faculty/cd/syllabus.html

The department and campus wide curriculum committees will review the syllabus to ensure that each of the items listed below are included. If items are missing or unclear, the proposed course change will be <u>denied</u>.

SYLLABUS CHECKLIST FOR ALL UAF COURSES

During the first week of class, instructors will distribute a course syllabus. Although modifications may be made throughout the semester, this document will contain the following information (as applicable to the discipline):

 Course information: □ Title, □ number, □ credits, □ prerequisites, □ location, □ meeting time
(make sure that contact hours are in line with credits).
2. Instructor (and if applicable, Teaching Assistant) information:
\square Name, \square office location, \square office hours, \square telephone, \square email address.
3. Course readings/materials:
☐ Course textbook title, ☐ author, ☐ edition/publisher.
□ Supplementary readings (indicate whether □ required or □ recommended) and
any supplies required.
4. Course description:
Content of the course and how it fits into the broader curriculum;Expected proficiencies required to undertake the course, if applicable.
☐ Inclusion of catalog description is <i>strongly</i> recommended, and
Description in syllabus must be consistent with catalog course description.
5. Course Goals (general), and (see #6)
6. ☐ Student Learning Outcomes (more specific)
7. Instructional methods:
Describe the teaching techniques (eg: lecture, case study, small group discussion, private instruction,
studio instruction, values clarification, games, journal writing, use of Blackboard, audio/video
conferencing, etc.).
8. Course calendar:
A schedule of class topics and assignments must be included. <u>Be specific</u> so that it is clear that the instructor has thought this through and will not be making it up on the fly (e.g. it is not adequate to say "lab". Instead, give each lab a title that describes its content). You may call the outline Tentative or Worl in Progress to allow for modifications during the semester.
9. Course policies:
☐ Specify course rules, including your policies on attendance, tardiness, class participation, make-up exams, and plagiarism/academic integrity.
10. Evaluation:
☐ Specify how students will be evaluated, ☐ what factors will be included, ☐ their relative value, and ☐ how they will be tabulated into grades (on a curve, absolute scores, etc.)
11. Support Services:
☐ Describe the student support services such as tutoring (local and/or regional) appropriate for the
course.
12. Disabilities Services: The Office of Disability Services implements the Americans with Disabilities Act (ADA), and insures that UAF students have equal access to the campus and course materials.
☐ State that you will work with the Office of Disabilities Services (208 WHIT, 474-5655) to provide reasonable accommodation to students with disabilities."

University of Alaska Fairbanks Electrical and Computer Engineering Department EE675 – Robot Modeling and Control Fall 2011

SYLLABUS AND COURSE INFORMATION

Lecture Time: TR (5:15-6:45 PM)

Room:TBA

2009 Catalog Description:

Introduction to basic concepts in robotics; homogeneous transformations; Denavit-Hartenberg parameters, forward and inverse kinematics; velocity kinematics, Jacobiens; dynamics and modeling; robot control: independent joint control, multivariable control, Lyapunov stability, PD+, computed torque, inverse dynamics control with the use of Matlab/Simulink, kinematics and control related demonstrations on the PUMA 560 manipulator.

Prerequisites: EE471 or equivalent in control; PHYS F211X/F212 or equivalent

Text: Introduction to Robotics: Mechanics and Control, Craig, 3rd edition, Pearson Prentice Hall, 2005

Instructor: Seta Bogosyan

Office: Duckering 221

Telephone: 474-2755

e-mail: ffsob@uaf.edu

Office Hours:

Wed: 1:00-4:00 PM; or by appointment.

COURSE POLICIES

Point Distribution:	Midterm I	20%
	Midterm II	20%
	Final Exam	25%
	Quizzes	10%
	Homework& Project	15%
	Class Performance	10%
	Total	100%

Assessment Criteria:

- → No late homework will be accepted unless previously authorized by the instructor. Work should be done on an individual basis.
- → Students are expected to know Matlab/Simulink software.
- → Two 60 minute midterms will be administered during the semester.
- → One 2-hour final will be administered at the end of the semester.
- Regular class attendance is strongly recommended and participation in class by asking relevant questions and answering the instructor's questions will be graded by the above mentioned percentage.
- Tests will be open/close book at the instructor's discretion.
- → There will be a course project that uses MATLAB/SIMULINK. Students are expected to present their project work and results in the form of a technical report.

University of Alaska Fairbanks Electrical and Computer Engineering Department EE675 – Robot Modeling and Control Fall 2011

Support Services:

Blackboard will be used to support instruction, specifically, to post past lectures, announcements, assignments, and solutions for tests and assignments.

DETAILED COURSE TOPICS:

Week 1,2	Introduction to robotics; basic concepts; homogeneous transformations
Week 3	Transformations cont'd; forward kinematics
Week 4	Denavit-Hartenberg parameters
Week 5	Inverse kinematics
Week 6	Velocity kinematics
Week 7	Jacobiens and force/torque relationships
Week 8	MIDTERM I
Week 9	Dynamics; Euler-Lagrange method
Week 10	Independent joint control of robots
Week 11	Review and MIDTERM II
Week 12	IJC cont'd; introduction to Lyapunov stability theory
Week 13	Multivariable control
Week 14	Feedforward control; PD+
Week 15	Inverse dynamics control
Week 16	FINAL (TBA)

Disabilities Services:

The Office of Disability Services implements the Americans with Disabilities Act (ADA), and insures that UAF students have equal access to the campus and course materials. The instructor, the teaching assistant, and the administrative assistant will work with the Office of Disabilities Services to provide reasonable accommodation to students with disabilities. Disability Services is located at the Center for Health and Counseling in 203 WHIT. The coordinator of Disability Services can be contacted by phone at 474-7043 or 474-7045 (TTY), and by email at fydso wuaf.edu.